UNIT-1:

- 1. Explain about 4-quadrant operation of DC Drive (Hoist Control)?
- 2. Explain briefly the following methods of braking of a D.C Motor
- (a) Regenerative braking
- (b) Dynamic braking
- (c) Plugging.
- 3. What is meant by Stability? Explain about Steady State Stability?
- 4. Write about Fundamental Torque equation with various notations present in it?
- 5. Explain about Load Equalization of DC Drive?

UNIT-2:

- 1. Distinguish between circulating current and non-circulating current mode of operation.
- 2. Explain Speed torque Characteristics of a dc series motor connected to a three ph fully controlled converter.
- 3. Explain Speed -Torque Characteristics of a dc separately excited motor connected to a three phase fully controlled converter.
- 4. Explain how four-quadrant operation is achieved by dual converters each of 3ph full wave configuration for dc separately excited motor.
- 5. What is a dual converter? Explain the principle of operation of a dual converter in circulating current mode. How the same is used for speed control of dc drive.